Universida_{de}Vigo

Subject Guide 2023 / 2024

IDENTIFYIN	<u> </u>				
Sistemas d					
Subject	Sistemas de				
	control				
Code	007M174V01105				
Study	Máster				
programme	Universitario en				
	Operaciones e				
	Ingeniería de				
	Sistemas Aéreos				
	no Tripulados				
Descriptors	ECTS Credits	Choose	Year	Quadmester	
	6	Optional	1st	2nd	
Teaching	#EnglishFriendly				
language	Spanish				
	Galician				
Department					
Coordinator					
Lecturers					
E-mail					
Web	http://aero.uvigo.es				
General	This course describes fundamental concepts, principles and techniques about unmanned aerial vehicles:				
description	geometry, mechanics, hardware, control and navigation.				
	English Friendly subject: International students may request from the teachers: a) materials and bibliographi references in English, b) tutoring sessions in English, c) exams and assessments in English.				

Training and Learning Results

Code

- A3 That the students be able to integrate knowledge and face the complexity of formulating judgments from information, which being incomplete or limited, includes reflections on social and ethical responsibilities linked to the application of their knowledge and judgments
- A4 That the students know how to communicate their conclusions and the latest knowledge and reasons that support them to specialized and non-specialized audiences in a clear and unambiguous manner
- A5 That students have the learning abilities that allow them to continue studying in a way that will have to be largely selfdirected and autonomous
- B3 That students acquire the capabilities to analyze the needs of a company in the field of unmanned aerial systems and determine the best technological solution for the same
- B4 That the students acquire the knowledge to develop unmanned aerial systems or to plan specific operations, depending on the existing needs and to apply the existing technological tools
- B5 That students know and be able to apply the principles and methodologies of research, such as bibliographical searches, data collection and analysis and interpretation thereof, as well as the presentation of conclusions, in a clear, concise and rigorous way
- D6 Ability to work as a team
- D7 Capacity for organization and planning
- D8 Ability of analysis and synthesis
- O9 Capacity for critical reasoning and creativity

Expected results from this subject	
Expected results from this subject	Training and
	Learning Results

cquire knowledge about unmanned aerial vehicles, their key components, state estimation, basic		A3
mechanics, design considerations, agility and	maneuverability.	A4
		A5
		B3
		B4
		D8
Kanan tha an anatala and an aban's alamas' alamas'	attende for an analysis of the bound of the state of the	
	ations of unmanned aerial vehicles, transformations,	A3
rotations, Euler angles, applicability of quater rotor, linearization.	nions, angular velocity, equations of movement of a multi-	A4 A5
rotor, illiearization.		B4
Understand the bases of the control and navig	gation system, PID controls, control in 1D, 2D and 3D of	A3
multirotor, generation of trajectories, Euler-La	grange equations and Splines.	A4
		A5
		B3
		B4
Understand the operation of multiple control	systems.	A3
		A4
		A5
		B4
		D6
Many the conce C avaid devices		D7
Know the sense & avoid devices.		A3
		A4
		A5 B4
		B5
Understand the basics of embedded systems	in real time	A3
Onderstand the basics of embedded systems	iii real tille.	A3 A4
		A5
		B4
		D6
		D7
Know the different existing open hardware co	ntrollers and their operation.	A3
3 .p	· · · · · · · · · · · · · · · · · · ·	A4
		A5
		B4
		B5
		D6
		D7
Contents		
Topic		
Introduction to unmanned aerial vehicles.	Multi-rotors.	
Key components of autonomous flight.	Estimation of states.	
	Basic mechanics	
	Design considerations	
	Agility and maneuverability	
	Selection of components.	
Geometry and mechanics.	Transformations	
	Rotations Angles of Fuler	
	Angles of Euler. Ouaternions	
	Angular velocity.	
	Newton-Euler equations.	
	Main axes and main moments of inertia.	
	Equations of movement of a multi-rotor.	
	Linearization	
Control and navigation.	PID control.	
3 · ·	1D, 2D and 3D control of multirotor.	
	Paths.	
	Euler-Lagrange equations.	
	Splines.	
Control of multiple systems.		
Sense & avoid devices.		
Fundamentals of embedded systems in real ti	me.	
Open hardware controllers.		

Planning			
	Class hours	Hours outside the classroom	Total hours
Lecturing	10	0	10
ICT suppoted practices (Repeated, Dont Use)	12.5	12.5	25
Problem solving	12.5	12.5	25
Seminars	3	0	3
Mentored work	8	72	80
Problem and/or exercise solving	2	5	7

^{*}The information in the planning table is for guidance only and does not take into account the heterogeneity of the students.

Methodologies	
	Description
Lecturing	Exhibition by the teacher of the contents on the subject.
ICT suppoted practices	Activities of application of knowledge to concrete situations and acquisition of basic and procedural
(Repeated, Dont Use)	skills related to the subject. They are developed through ICT in an autonomous way.
Problem solving	Activity in which problems related to the subject are formulated. The students must develop the solutions. The objective is that the students apply the theoretical contents in the resolution of small programming problems.
Seminars	Orientation activity for students.
Mentored work	The student, individually or in groups, prepares a document on the topic of the subject or prepares seminars, investigations, reports, essays, summaries of readings, conferences, etc.

Personalized assistance			
Methodologies	Description		
Mentored work	Tutorials in the teacher's office. It is advisable to go to these tutorials when difficulties appear in the development of the supervised work, or when the time dedicated to the non-contact activities significantly exceeds the time set in the planning.		
ICT suppoted practices (Repeated, Dont Use)	Tutorials in the teacher's office. It is advisable to attend these tutorials when difficulties arise in the development of autonomous practices through ICT, or when the time spent on noncontact activities significantly exceeds the time set in the planning.		

Assessment					
	Description	Qualification		ainin Learı Resı	ning
	s 2 assignments of autonomous practices through ICT, each one will contribute 15% of the overall mark for this course	30			D8 D9
Mentored work	1 assignment of supervised work, it will contribute 20% of the overall mark for this course	20	A3 A4 A5	B3 B4 B5	D6 D7 D8 D9
Problem and/or exercise solving	2 written exams, short answer tests, about the contents and competences taught in the lectures and autonomous practices through ICT. These tests will be short answer, each one will contribute 25% of the overall mark for this course.	50		B3 B4	D8 D9

Other comments on the Evaluation

ASSESSMENT FOR ASSISTANTS IN 1ST EDITION: CONTINUOUS EVALUATION.

For the students attending the 1st edition (continuous evaluation) the following tests and deliveries will be made:

- 1 assignment of supervised work, it will contribute 20% of the overall mark for this course;
- 2 assignments of autonomous practices through ICT, each one will contribute 15% of the overall mark for this course;
- 2 written exams, short answer tests, about the contents and competences taught in the lectures and autonomous practices through ICT. These tests will be short answer, each one will contribute 25% of the overall mark for this course.

To pass the subject it is mandatory that the student make all the assignments and all the written exams, and that in each

assignment and written exam obtain a mark equal to or higher than 4.0.

In the case of not making any assignments or written exam, or obtain in any assignments or written exam a mark lower than 4.0, if the overall mark is higher than 5, the final mark in the minutes will be 4.9, fail.

ASSESSMENT FOR NON ASSISTANTS IN 1ST EDITION.

For the students attending the 1st edition (non continuous evaluation) the following tests and deliveries will be made:

- 1 assignment of supervised work, it will contribute 20% of the overall mark for this course;
- 2 assignments of autonomous practices through ICT, each one will contribute 15% of the overall mark for this course;
- 1 written exam about the contents and competences taught in the lectures and autonomous practices through ICT. This test will be short answer and it will contribute 50% of the overall mark for this course.

To pass the subject it is mandatory that the student make all the assignments and all the written exams, and that in each assignment and written exam obtain a mark equal to or higher than 4.0.

In the case of not making any assignments or written exam, or obtain in any assignments or written exam a mark lower than 4.0, if the overall mark is higher than 5, the final mark in the minutes will be 4.9, fail.

ASSESSMENT FOR 2ST EDITION AND OTHER EDITIONS

The same assessment for non assisstans in 1st edition

JUSTIFICATION OF ABSENCE

To be able to justify the absence to a exam is required a Certificate of Absence or a Consultation and Hospitalization Certificate (also called P10) issued by the SERGAS doctor, or a certificate issued by a doctor. A proof of the doctor's appointment will not be valid

Sources of information

Basic Bibliography

Randal Beard, Timothy McLain, Small Unmanned Aircraft: Theory and Practice, Princeton University Press, 2012

Complementary Bibliography

Michael Cook, A Linear Systems Approach to Aircraft Stability and Control, Butterworth-Heinemann, 2007

Katsuhiro Ogata, Ingeniería de control moderna, PRENTICE HALL, 2010

Hassan Gomaa, Real-time software design for embedded systems, Cambridge University Press, 2016

Plamen Angelov, Sense and Avoid in UAS Research and Applications, John Wiley & Sons, Ltd, 2012

www.librepilot.org,

Recommendations

Subjects that it is recommended to have taken before

Unmanned aerial systems operations/O07M174V01102 On-board sensors/O07M174V01104