Universida_{de}Vigo

Subject Guide 2015 / 2016

IDENTIFYIN Automation	and Control Fundamentals			
Subject	Automation and			
	Control			
	Fundamentals	,		
Code	V12G320V01405			
Study	(*)Grao en			
programme	Enxeñaría Eléctrica			
Descriptors	ECTS Credits	Choose	Year	Quadmester
	6	Mandatory	2nd	2nd
Teaching	Spanish			
language				
Department				
Coordinator	Vázquez Núñez, Fernando Antonio			
Lecturers	Vázquez Núñez, Fernando Antonio			
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Web				
General description	This matter presents the basic concepts of the syste considering like central elements of the same the process of the proce			

Competencies

Code

- B3 CG3 Knowledge in basic and technological subjects that will enable students to learn new methods and theories, and provide them the versatility to adapt to new situations.
- C12 CE12 Know the fundamentals of automation and control methods.
- D2 CT2 Problems resolution.

respectively.

- D3 CT3 Oral and written proficiency in the own language.
- D6 CT6 Application of computer science in the field of study.
- D9 CT9 Apply knowledge.
- D16 CT16 Critical thinking.
- D17 CT17 Working as a team.
- D20 CT20 Ability to communicate with people not expert in the field.

Learning outcomes				
Expected results from this subject		Training and Learning Results		
systems.			D9	
			D16	
Know which are the elements that constitute an industrial automation system, how they work and	В3	C12		
how the are dimensioned.				
Capacity to design and project a complete automation system.		C12	D2	
			D3	
			D6	
			D9	
			D17	
			D20	
Understand the fundamentals of programmable logic controllers and their application in		C12	D2	
automating different types of industrial plants.			D6	
			D9	
			D16	

Contents	
Торіс	

1. Introduction to industrial automation (2,5C) Introduction to issues that will allow the student to value the capabilities and knowledge that will be obtained during the course. 1.1 Course presentation. 1.2 Why are industrial processes automated? 1.3 Historical evolution of automation: from regulating simple movements to supply chain management. 1.4 Economic and social impact. 1.5 Role of the Electrical Engineer. 1.6 Types of automation and examples. Presentation of the elements that are commonly used to automate 2. Automation elements (2C) industrial processes. 2.1 Sensors 2.1.1 Presence 2.1.2 Rotation and speed 2.1.3 Translation 2.1.4 Encoder 2.1.4 Others: temperature, pressure, etc. 2.2 Simple actuators 2.2.1 Electrical engines 2.2.2 Cylinders 2.2.3 Pumps 2.2.4 Valves 2.2.5 Contactors 2.3 Complex actuators 2.3.1 Linear actuators 2.3.2 Two-axis actuators 2.3.3 Conveyors 2.3.4 Cranes 2.3.5 Robots and manipulators 2.3.6 In-plant transport systems 2.3.7 In-plant storage systems 2.4 Plant control elements 2.4.1 Industrial regulator 2.4.2 Frequency variator 2.4.3 Automaton 2.4.4 Control by PC 2.4.5 Industrial communications 2.5 Monitoring and management systems. 2.5.1 SCADA 2.5.2 MES 3. Introduction to programmable logic controllers Introduce basic concepts relative to the design and development of automation systems based on Programmable Logic Controllers (PLC) (2C) 3.1 Basic concepts 3.1.1 Physical and logical architecture 3.1.2 Numbering systems 3.1.3 Program cycle 3.1.4 Set-up 3.1.5 Modular programming 3.2 Basic elements 3.2.1 Inputs 3.2.2 Outputs 3.2.3 Memory 3.2.4 Counters 3.2.5 Timers 3.3 Operations 3.3.1 Memory transfer 3.3.2 Combinatorial logic 3.3.3 Arithmetic 3.4 Low level languages 3.5 High level languages 3.6 Advanced functions

4. Low level programming of PLCs (6C)	Students learn to develop binary automation systems using a contact diagram language 4.1 Contact diagrams concepts 4.2 Binary variables 4.3 Combinatory systems 4.4 Sequential systems 4.5 Arithmetic operations 4.6 Counters 4.7 Timers 4.8 Examples
5. Systems modeling for programming PLCs (8C)	
5. Systems modeling for programming rices (66)	Grafcet.
	5.1 Basic principles. Modeling techniques.
	5.2 Modeling using Petri Nets.
	5.2.1 Definition of stages and transitions. Rules of evolution.
	5.2.2 Conditional selection of alternatives.5.2.3 Simultaneous sequences. Concurrence. Shared resource.
	5.3 Implementation of Petri Nets.
	5.3.1 Direct implementation
	5.3.2 Normalized implementation (Grafcet)
	5.4 Design of basic industrial automation systems.
C. Labord and an Earth and a street of the same of the	5.5 Examples.
6. Introduction to the automatic regulation and systems modeling (4C)	Introduce the basic concepts related to automatic regulation of continuous linear systems
systems modeling (40)	6.1 Open loop and closed loop regulation systems.
	6.2 The typical regulation loop. Nomenclature, definitions and
	specifications.
	6.3 Physical systems and mathematical models.
	6.3.1 Mechanical Systems. 6.3.2 Electrical Systems.
	6.3.3 Others.
	6.4 Transfer function modeling.
	6.4.1 Laplace Transform.
	6.4.2 Properties.
7. Continuous process control (6C)	6.4.3 Examples. Students learn to design and tune industrial regulators.
7. Continuous process control (oc)	7.1 Continuous linear controllers.
	7.1.1 Control actions: proportional, integral and derivative.
	7.1.2 PID regulator.
	7.2 Empirical methods for tuning industrial regulators.7.2.1 Open loop tuning.
	7.2.2 Closed loop tuning.
	7.3 Examples.
8. Process control using a PLC (2C)	Students learn to implement a PID using a PLC
	8.1 Functional blocks for process control
	8.2 PID implementation.8.3 Monitoring and control software (SCADA).
P1. Introduction to STEP7 and programming	Introduction to the STEP7 environment, that allows programming Siemens
languages (2L)	series S7-300 and S7-400 PLCs, as well as testing them, storing them,
	modifying them, etc Familiarization with the environment, hardware
	configuration and low level programming languages, by implementing a
P2. Direct modelling and implementation (2L)	simple example. Model a simple automation example and implement it as a contact
1 2. Direct modelling and implementation (22)	diagram.
P3. Petri Net modelling and implementation (6L)	Model a more complex example and implement it in one of the languages
	available in STEP7.
P4. S7-Graph modelling and implementation (2L)	
with Matlab/Simulink (2L)	Introduction to the basic elements of Matlab/Simulink as well as to the control toolbox.
Mai Pidday Sillidilik (ZL)	Analyze and simulate the transitory response of first and second order
	continuous systems.
	Analysis and simulation of linear control systems with Matlab/Simulink.
and Simulink (2L)	
P7. Industrial regulator tuning (2L)	Determination of the parameters of a PID regulator using the methods
	studied in class. Implementation in an industrial regulator connected to a personal computer where the plant model is simulated.

	Class hours	Hours outside the classroom	Total hours
Troubleshooting and / or exercises	0	10	10
Laboratory practises	18	27	45
Master Session	32.5	32.5	65
Long answer tests and development	3	19	22

^{*}The information in the planning table is for guidance only and does not take into account the heterogeneity of the students.

Methodologies			
	Description		
Troubleshooting and / o	or The profesor will solve problems and exercises in the classroom and the students will have to		
exercises	resolve similar exercises to obtain the necessary skills		
Laboratory practises	Concepts explained in the classroom are applied to specific situations and solved using tools commonly found in the workplace		
Master Session	Exhibition by part of the professor of the contents of the matter		

Personalized atte	ention
Methodologies	Description
Master Session	In order to achieve an effective use of the students' time, the profesor will personally solve their doubts and questions. This will occur during lectures and laboratory classes as well as in tutorships. To attend tutorships, the students will have to previously establish an appointment with the professor. For this, he will have to send him an and-mail describing his specific doubts. When possible, the professor will try to resolve the doubts by e-mail and will put a copy of the question and response in Faitic so that all the students can see them. If necessary, the profesor will assign a slot of time on a specific date to meet in person with the student. The professor will not provide tutorship sessions without a previous appointment. The students also will be able to formulate his doubts through *Faitic.
Troubleshooting and / or exercises	In order to achieve an effective use of the students' time, the profesor will personally solve their doubts and questions. This will occur during lectures and laboratory classes as well as in tutorships. To attend tutorships, the students will have to previously establish an appointment with the professor. For this, he will have to send him an and-mail describing his specific doubts. When possible, the professor will try to resolve the doubts by e-mail and will put a copy of the question and response in Faitic so that all the students can see them. If necessary, the profesor will assign a slot of time on a specific date to meet in person with the student. The professor will not provide tutorship sessions without a previous appointment. The students also will be able to formulate his doubts through *Faitic.
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Assessment					
	Description	Qualification	Training and Learning Results		
Laboratory practises	Continuous evaluation of each student's work will be assed during a total of 9 lab sessions, scoring each session between 0 and 10 points. The grade for lab practices will be the average of the scores obtained in the sessions.	30	C1	.2 D2 D6 D9 D1 D1 D2	6) 16 17
Long answer tests and development	Each final examination will include a test of 10 questions and a problem.	70	B3 C1	.2 D2 D3 D9 D1	3)

Other comments on the Evaluation

For each session the profesor will establish specific targets/deliverables, even when the practice covers several sessions.

Evaluation of practical sessions:

Assistance: 3 pointsParticipation: 2 points

• Approach of the problem and of the solution: 2 points

• Correct solution: 3 points

The grade for laboratory practices is saved for the second evaluation if the student has passed them and does not decline continuous evaluation. It is not saved for other course years.

Students that have passed the practices during the continuous evaluation will be able to pass the subject if their score in the exam is of at least 3 points and the total is at least 5 points.

Students that have not passed the practices during the continuous evaluation or decline, will have to pass a practical examination if they pass the final examination (5 points over 10) in any one of the two final course evaluations.

Ethical commitment: It is expected an adequate ethical behaviour of the student. In case of detecting unethical behaviour (copying, plagiarism, unauthorized use of electronic devices, etc.) shall be deemed that the student does not meet the requirements for passing the subject. In this case, the overall rating in the current academic year will be Fail (0.0).

Sources of information

Básic:

"Autómatas Programables y Sistemas de Automatización",

E.MANDADO, J.MARCOS, CELSO FERNANDEZ, J.I.ARMESTO, Ed. Marcombo 2009

□Las Redes de Petri en la Automática y la Informática , MANUEL SILVA Editorial AC

"Sistemas de control modernos", DORF, BISHOP, Ed. Addison-Wesley.

Additional:

"Autómatas Programables. Fundamento. Manejo. Instalación y Práctica",

PORRAS, A., MONTERO, A.P., Ed. McGraw-Hill, 1990.

"Automatización. Problemas resueltos con autómatas programables□, J. Pedro Romera, J. Antonio Lorite, Sebastián Montoro. Ed. Paraninfo

□Guía usuario Step7 SIEMENS

□Diagrama de funciones (FUP) para S7-300 y S7-400□ SIEMENS

□SIMATIC S7-GRAPH para S7-300/400□ SIEMENS

"Control de sistemas continuos. Problemas resueltos", Barrientos, Ed. Mcgraw-Hill.

"Ingeniería de control moderna", Ogata, K., Ed. Prentice-hall.

"Retroalimentación y sistemas de control", DISTEFANO, J.J., STUBBERUD, A.R., WILLIAMS, I.J., Ed. McGraw-Hill.

Recommendations

Other comments

Requirements: To register for this module the student must have passed or be registered for all the modules of the previous year.